**Automated Theorem Proving** Lecture 6: General Resolution

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Propositional (ground) resolution:

refutationally complete,

in its most naive version:

not guaranteed to terminate for satisfiable sets of clauses,

(improved versions do terminate, however)

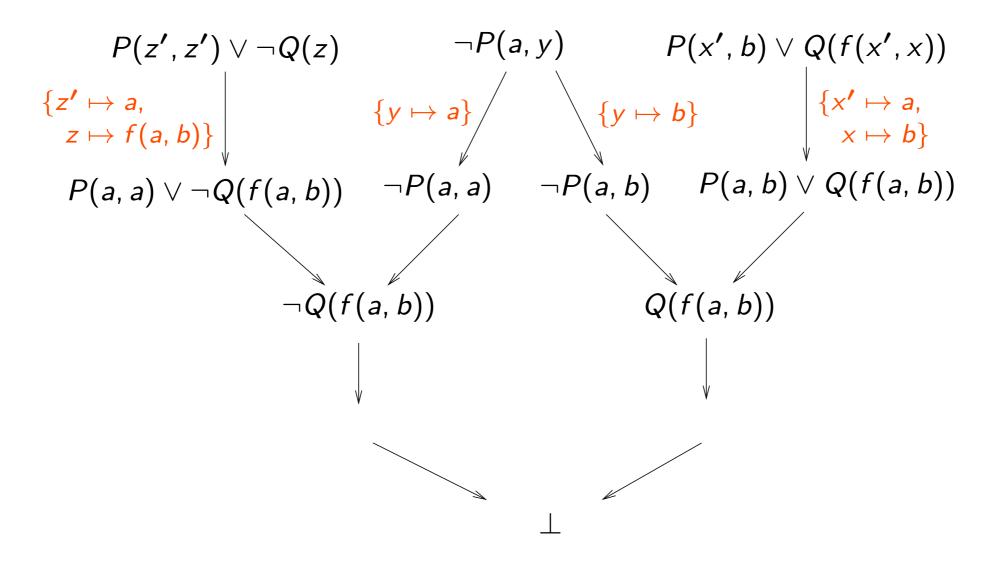
inferior to the CDCL procedure.

But in contrast to the CDCL procedure, resolution can be easily extended to nonground clauses.

If  $\mathcal{A}$  is a model of an (implicitly universally quantified) clause C, then by Lemma 3.3.8 it is also a model of all (implicitly universally quantified) instances  $C\sigma$  of C.

Consequently, if we show that some instances of clauses in a set N are unsatisfiable, then we have also shown that N itself is unsatisfiable.

Idea: instantiate clauses appropriately:



Early approaches (Gilmore 1960, Davis and Putnam 1960):

Generate ground instances of clauses.

Try to refute the set of ground instances by resolution.

If no contradiction is found, generate more ground instances.

Problems:

More than one instance of a clause can participate in a proof.

Even worse: There are infinitely many possible instances.

Observation:

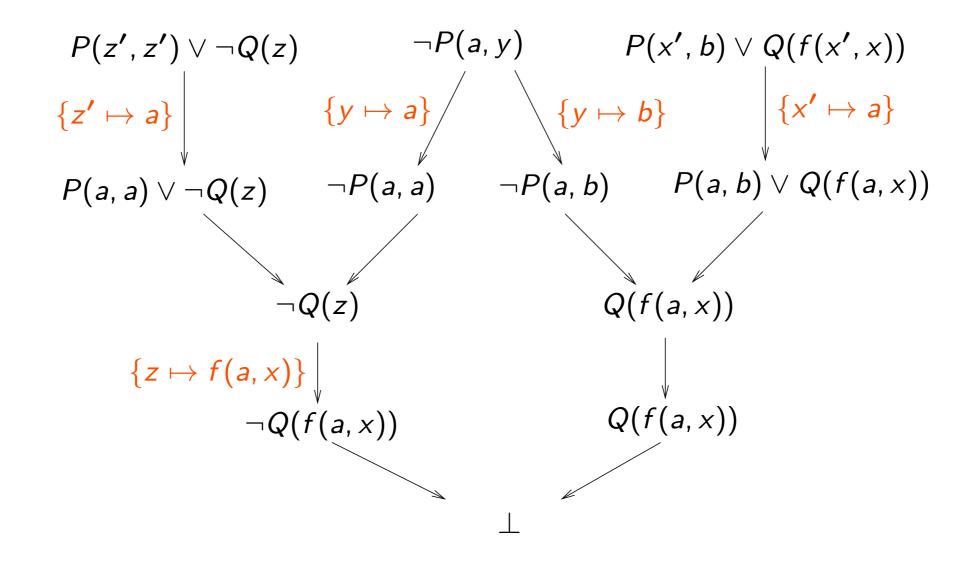
Instantiation must produce complementary literals (so that inferences become possible).

Idea (Robinson 1965):

Do not instantiate more than necessary to get complementary literals  $\Rightarrow$  most general unifiers (mgu).

Calculus works with nonground clauses; inferences with nonground clauses represent infinite sets of ground inferences which are computed simultaneously  $\Rightarrow$  lifting principle.

Computation of instances becomes a by-product of boolean reasoning.



## Unification

Let  $E = \{s_1 \doteq t_1, \ldots, s_n \doteq t_n\}$  ( $s_i, t_i$  terms or atoms) be a multiset of equality problems. A substitution  $\sigma$  is called a unifier of E if  $s_i \sigma = t_i \sigma$  for all  $1 \le i \le n$ .

If a unifier of E exists, then E is called unifiable.

## Unification

A substitution  $\sigma$  is called more general than a substitution  $\tau$ , denoted by  $\sigma \leq \tau$ , if there exists a substitution  $\rho$  such that  $\rho \circ \sigma = \tau$ , where  $(\rho \circ \sigma)(x) := (x\sigma)\rho$  is the composition of  $\sigma$  and  $\rho$  as mappings. (Note that  $\rho \circ \sigma$  has a finite domain as required for a substitution.)

If a unifier of E is more general than any other unifier of E, then we speak of a most general unifier of E, denoted by mgu(E).

Proposition 3.10.1:

- (i)  $\leq$  is a quasi-ordering on substitutions, and  $\circ$  is associative.
- (ii) If  $\sigma \leq \tau$  and  $\tau \leq \sigma$  (we write  $\sigma \sim \tau$  in this case), then  $x\sigma$  and  $x\tau$  are equal up to (bijective) variable renaming, for any x in X.
- A substitution  $\sigma$  is called idempotent if  $\sigma \circ \sigma = \sigma$ .

Proposition 3.10.2:

 $\sigma$  is idempotent if and only if dom $(\sigma) \cap \operatorname{codom}(\sigma) = \emptyset$ .

## **Rule-Based Naive Standard Unification**

$$t \doteq t, E \Rightarrow_{SU} E$$

$$f(s_1, \dots, s_n) \doteq f(t_1, \dots, t_n), E \Rightarrow_{SU} s_1 \doteq t_1, \dots, s_n \doteq t_n, E$$

$$f(\dots) \doteq g(\dots), E \Rightarrow_{SU} \bot$$

$$if f \neq g$$

$$x \doteq t, E \Rightarrow_{SU} x \doteq t, E\{x \mapsto t\}$$

$$if x \in var(E), x \notin var(t)$$

$$x \doteq t, E \Rightarrow_{SU} \bot$$

$$if x \neq t, x \in var(t)$$

$$t \doteq x, E \Rightarrow_{SU} x \doteq t, E$$

$$if t \notin X$$

## **Properties of SU**

If  $E = \{x_1 \doteq u_1, \dots, x_k \doteq u_k\}$ , with  $x_i$  pairwise distinct,  $x_i \notin var(u_j)$ , then *E* is called an (equational problem in) solved form representing the solution  $\sigma_E = \{x_1 \mapsto u_1, \dots, x_k \mapsto u_k\}.$ 

Proposition 3.10.3:

If E is a solved form then  $\sigma_E$  is an mgu of E.

## **Properties of SU**

Theorem 3.10.4:

- 1. If  $E \Rightarrow_{SU} E'$  then  $\sigma$  is a unifier of E if and only if  $\sigma$  is a unifier of E'
- 2. If  $E \Rightarrow_{SU}^* \bot$  then *E* is not unifiable.
- 3. If  $E \Rightarrow_{SU}^{*} E'$  with E' in solved form, then  $\sigma_{E'}$  is an mgu of E.

## **Main Unification Theorem**

Theorem 3.10.5:

*E* is unifiable if and only if there is a most general unifier  $\sigma$  of *E* such that  $\sigma$  is idempotent and dom $(\sigma) \cup$  codom $(\sigma) \subseteq$  var(E).

Example 3.10.6: We unify g(x, f(x)) and g(b, y) using standard unification:

$$g(x, f(x)) \doteq g(b, y)$$
  

$$\Rightarrow_{SU} x \doteq b, f(x) \doteq y$$
  

$$\Rightarrow_{SU} x \doteq b, f(b) \doteq y$$
  

$$\Rightarrow_{SU} x \doteq b, y \doteq f(b)$$
  

$$\Rightarrow_{SU} x \doteq b, y \doteq f(b)$$

Resulting substitution:  $\{x \mapsto b, y \mapsto f(b)\}$ .

## **Exponential Growth of SU**

Problem: Using  $\Rightarrow_{SU}$ , an *exponential growth* of terms is possible.

Example 3.10.7: We unify g(x, y, z) and g(f(y, y), f(z, z), f(a, a)) using SU:  $g(x, y, z) \doteq g(f(y, y), f(z, z), f(a, a))$   $\Rightarrow_{SU} x \doteq f(y, y), y \doteq f(z, z), z \doteq f(a, a)$   $\Rightarrow_{SU} x \doteq f(f(z, z), f(z, z)), y \doteq f(z, z), z \doteq f(a, a)$   $\Rightarrow_{SU} x \doteq f(f(f(a, a), f(z, a)), f(f(a, a), f(a, a))), y \doteq f(f(a, a), f(a, a)),$  $z \doteq f(a, a)$ 

Resulting substitution:  $\{x \mapsto f(f(f(a, a), f(a, a)), f(f(a, a), f(a, a))), y \mapsto f(f(a, a), f(a, a)), z \mapsto f(a, a)\}$ .

## **Rule-Based Polynomial Unification**

The following unification algorithm avoids the exponential growth problem, at least if the final solved form is represented as a DAG.

$$t \doteq t, E \Rightarrow_{PU} E$$

$$f(s_1, \dots, s_n) \doteq f(t_1, \dots, t_n), E \Rightarrow_{PU} s_1 \doteq t_1, \dots, s_n \doteq t_n, E$$

$$f(\dots) \doteq g(\dots), E \Rightarrow_{PU} \bot$$

$$if \ f \neq g$$

$$x \doteq y, E \Rightarrow_{PU} x \doteq y, E\{x \mapsto y\}$$

$$if \ x \in var(E), x \neq y$$

$$x_1 \doteq t_1, \dots, x_n \doteq t_n, E \Rightarrow_{PU} \bot$$

$$if \ there \ are \ positions \ p_i \ with$$

$$t_i|_{p_i} = x_{i+1}, t_n|_{p_n} = x_1$$

$$and \ some \ p_i \neq \varepsilon$$

# **Rule-Based Polynomial Unification**

$$x \doteq t, E \Rightarrow_{PU} \bot$$
  
if  $x \neq t, x \in var(t)$   
 $t \doteq x, E \Rightarrow_{PU} x \doteq t, E$   
if  $t \notin X$   
 $x \doteq t, x \doteq s, E \Rightarrow_{PU} x \doteq t, t \doteq s, E$   
if  $t, s \notin X$  and  $|t| \le |s|$ 

Theorem 3.10.8:

- 1. If  $E \Rightarrow_{PU} E'$  then  $\sigma$  is a unifier of E if and only if  $\sigma$  is a unifier of E'
- 2. If  $E \Rightarrow_{PU}^* \bot$  then *E* is not unifiable.
- 3. If  $E \Rightarrow_{PU}^{*} E'$  with E' in solved form, then  $\sigma_{E'}$  is an mgu of E.

The solved form of  $\Rightarrow_{PU}$  is different from the solved form obtained from  $\Rightarrow_{SU}$ . To obtain the unifier  $\sigma_{E'}$ , we have to sort the list of equality problems  $x_i \doteq t_i$  in such a way that  $x_i$  does not occur in  $t_j$  for j < i, and then we have to compose the substitutions  $\{x_1 \mapsto t_1\} \circ \cdots \circ \{x_k \mapsto t_k\}$ .

# Example of PU

Example 3.10.9:

We unify g(x, f(x)) and g(b, y) using polynomial unification:

$$g(x, f(x)) \doteq g(b, y)$$
$$\Rightarrow_{PU} x \doteq b, f(x) \doteq y$$
$$\Rightarrow_{PU} x \doteq b, y \doteq f(x)$$

Resulting substitution:  $\{x \mapsto b\} \circ \{y \mapsto f(x)\} = \{x \mapsto b, y \mapsto f(b)\}.$ 

## **Polynomial Growth of PU**

Example 3.10.10:

We unify g(x, y, z) and g(f(y, y), f(z, z), f(a, a)) using PU:

$$g(x, y, z) \doteq g(f(y, y), f(z, z), f(a, a))$$
  
$$\Rightarrow_{PU} x \doteq f(y, y), y \doteq f(z, z), z \doteq f(a, a)$$
  
$$= z \doteq f(a, a), y \doteq f(z, z), x \doteq f(y, y)$$

Resulting substitution:  $\{z \mapsto f(a, a)\} \circ \{y \mapsto f(z, z)\} \circ \{x \mapsto f(y, y)\}.$ 

### **Resolution for General Clauses**

We obtain the resolution inference rules for nonground clauses from the inference rules for ground clauses by replacing equality by unifiability:

**General resolution** *Res*:

$$\frac{C \lor B \qquad C \lor \neg A}{(D \lor C)\sigma} \quad \text{if } \sigma = \text{mgu}(A, B) \qquad [\text{resolution}]$$
$$\frac{C \lor A \lor B}{(C \lor A)\sigma} \qquad \text{if } \sigma = \text{mgu}(A, B) \qquad [\text{factorization}]$$

For inferences with more than one premise, we assume that the variables in the premises are (bijectively) renamed such that they become different to any variable in the other premises.

We do not formalize this. Which names one uses for variables is otherwise irrelevant.

#### **Resolution for General Clauses**

Example 3.10.11: Consider the clauses

$$P(z', z') \lor \neg Q(z)$$
(1)  
 
$$\neg P(a, y)$$
(2)  
 
$$P(x', b) \lor Q(f(x', x))$$
(3)

From (1) and (2), using "Resolution" we obtain  $\neg Q(z)$  (4). From (3) and (2), using "Resolution" we obtain Q(f(a, x)) (5). From (5) and (4), using "Resolution" we obtain the empty clause.

## Lifting Lemma

Lemma 3.10.12: Let C and D be variable-disjoint clauses. If

 $\begin{array}{ccc}
D & C \\
\downarrow \theta_1 & \downarrow \theta_2 \\
\hline
D\theta_1 & C\theta_2 \\
\hline
C'
\end{array}$ [ground resolution]

then there exists a substitution  $\rho$  such that

$$\frac{D \quad C}{C''} \qquad [general resolution]$$
$$\downarrow \rho$$
$$C' = C'' \rho$$

An analogous lifting lemma holds for factorization.

## **Saturation of Sets of General Clauses**

Corollary 3.10.13:

Let N be a set of general clauses saturated under Res, i.e.,  $Res(N) \subseteq N$ . Then also  $G_{\Sigma}(N)$  is saturated, that is,

 $Res(G_{\Sigma}(N)) \subseteq G_{\Sigma}(N).$ 

## **Soundness for General Clauses**

Proposition 3.10.14:

The general resolution calculus is sound.

### Herbrand's Theorem

Lemma 3.10.15: Let N be a set of  $\Sigma$ -clauses, let  $\mathcal{A}$  be an interpretation. Then  $\mathcal{A} \models N$  implies  $\mathcal{A} \models G_{\Sigma}(N)$ .

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Lemma 3.10.16:
Let N be a set of \Sigma-clauses, let \mathcal{A} be an Herbrand interpretation.
Then \mathcal{A} \models G_{\Sigma}(N) implies \mathcal{A} \models N.
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Theorem 3.10.17 (Herbrand): A set N of  $\Sigma$ -clauses is satisfiable if and only if it has an Herbrand model over  $\Sigma$ .

Corollary 3.10.18: A set N of  $\Sigma$ -clauses is satisfiable if and only if its set of ground instances  $G_{\Sigma}(N)$  is satisfiable.

## **Refutational Completeness of General Resolution**

Theorem 3.10.19:

Let N be a set of general clauses that is saturated w.r.t. Res.

Then  $N \models \bot$  if and only if  $\bot \in N$ .

## **3.11 Theoretical Consequences**

We get some classical results on properties of first-order logic as easy corollaries.

## The Theorem of Löwenheim-Skolem

Theorem 3.11.1 (Löwenheim–Skolem):

Let  $\Sigma$  be a countable signature and let S be a set of closed  $\Sigma$ -formulas. Then S is satisfiable if and only if S has a model over a countable universe.

There exist more refined versions of this theorem. For instance, one can show that if S has some infinite model, then S has a model with a universe of cardinality  $\kappa$  for every  $\kappa$  that is larger than or equal to the cardinality of the signature  $\Sigma$ .

Theorem 3.11.2 (Compactness Theorem for First-Order Logic): Let S be a set of closed first-order formulas. S is unsatisfiable  $\Leftrightarrow$  some finite subset  $S' \subseteq S$  is unsatisfiable.