

Overview

Introduction

Tractable cases

DPLL algorithms

CDCL solvers

Probabilistic algorithms

Lookahead-based solvers

Applications

Bounded Model Checking

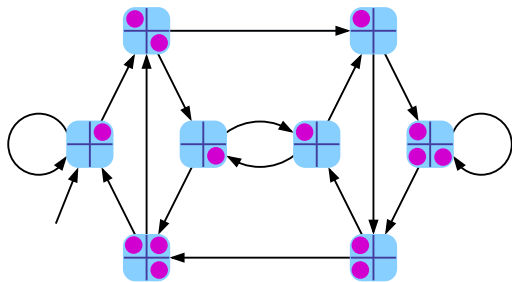
Random formulas

Model Checking

Technique for automated verification of

- ▶ hardware
- ▶ software
- ▶ communication protocols

Modeled as **labelled transition systems**,
properties described and verified in **temporal logic**.



Labelled transition systems

A **labelled transition system** $M = (S, I, T, \ell)$ consists of

- ▶ a finite set S of **states**,
- ▶ a subset $I \subseteq S$ of **initial states**,
- ▶ a **transition relation** $T \subseteq S \times S$,
- ▶ a labelling function $\ell : S \rightarrow 2^P$,
where P is a finite set of **elementary propositions**.

$p \in \ell(s)$ for $s \in S$ and $p \in P$ means:

Proposition p holds in state s .

Linear temporal logic: syntax

Formulas of *LTL* are inductively defined:

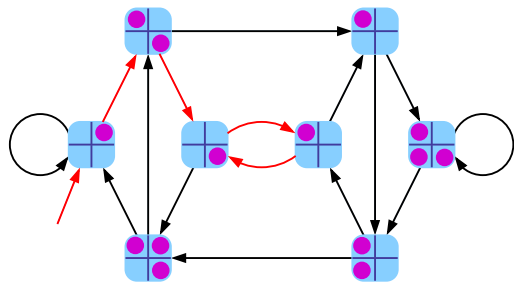
- ▶ The constants tt and ff are formulas.
- ▶ p und $\neg p$ are formulas, for every proposition $p \in P$.
- ▶ If φ is a formula, then $X\varphi$, $F\varphi$ and $G\varphi$ are formulas.
- ▶ If φ and ψ are formulas,
then $\varphi \wedge \psi$, $\varphi \vee \psi$, $\varphi U \psi$ and $\varphi R \psi$ are formulas.

Note that formulas of *LTL* are in *NNF* by definition.

For simplicity we consider only the fragment without U and R .

Model Checking *LTL*: Example

exists a path satisfying $G(UL \vee X UL)$



Linear temporal logic: semantics

A **path** π in M is an infinite sequence s_0, s_1, s_2, \dots of states s.t. $T(s_i, s_{i+1})$ for all i .

For a path π and $i \in \mathbb{N}$ let π^i denote the suffix $s_i, s_{i+1}, s_{i+2}, \dots$

The statement that $\pi \models \varphi$ is defined inductively:

$\pi \models p$	iff $p \in \ell(s_0)$
$\pi \models \neg p$	iff $p \notin \ell(s_0)$
$\pi \models X\varphi$	iff $\pi^1 \models \varphi$
$\pi \models F\varphi$	iff $\pi^i \models \varphi$ for some $i \geq 0$
$\pi \models G\varphi$	iff $\pi^i \models \varphi$ for all $i \geq 0$

$M \models \varphi$ holds if $\pi \models \varphi$ for some path π in M with $s_0 \in I$.

Classical model checking

Automata-based Model Checking (Vardi and Wolper 1986)

- ▶ Translate φ to Büchi automaton A_φ
- ▶ Compute product automaton $M \times A_\varphi$
- ▶ Use graph algorithms to find accepting run

Problem: state space explosion!

Symbolic model checking

Symbolic Model Checking (McMillan et al. 1990)

- ▶ Represent states of M as **bitvectors**
- ▶ transitions, propositions etc. as **boolean functions**
 - ▶ $f_I : \{0, 1\}^n \rightarrow \{0, 1\}$ with $f_I(s) = 1$ iff $s \in I$,
 - ▶ $f_T : \{0, 1\}^{2n} \rightarrow \{0, 1\}$ with $f_T(s, s') = 1$ iff $(s, s') \in T$,
 - ▶ $f_p : \{0, 1\}^n \rightarrow \{0, 1\}$ for each $p \in P$, with $f_p(s) = 1$ iff $p \in \ell(s)$.
- ▶ can be stored succinctly as **OBDDs**
- ▶ use efficient **OBDD algorithms** to evaluate φ

Bounded model checking

Symbolic model checking

\rightsquigarrow transition system represented in propositional logic

Idea: Take advantage of progress in SAT solvers

Problem with Complexity: *LTL* model checking is PSPACE-complete

Solution: Bounded model checking (Biere et al., 1999)

\exists path of length k satisfying φ ?

in NP \rightsquigarrow reducible to SAT

Bounded Semantics for LTL

A k -loop is a path $\pi = s_1, \dots, s_k, s_{k+1}, \dots$

with $s_{k+1+i} = s_{\ell+i}$ for some $\ell \leq k$ and all $i \in \mathbb{N}$.

If π is a k -loop, then $\pi \models_k \varphi$ iff $\pi \models \varphi$.

If π is not a k -loop, then $\pi \models_k \varphi$ iff $\pi \models_k^0 \varphi$,

where $\pi \models_k^i \psi$ is inductively defined by:

$$\pi \models_k^i p \quad \text{iff } p \in \ell(s_i)$$

$$\pi \models_k^i \neg p \quad \text{iff } p \notin \ell(s_i)$$

$$\pi \models_k^i X\varphi \quad \text{iff } i < k \text{ und } \pi \models_k^{i+1} \varphi$$

$$\pi \models_k^i F\varphi \quad \text{iff } \pi \models_k^j \varphi \text{ for some } j \text{ with } i \leq j \leq k$$

$$\pi \models_k^i G\varphi \quad \text{never holds}$$

Properties of the bounded semantics

Underapproximation: if $\pi \models_k \varphi$, then $\pi \models \varphi$.

Theorem

For every M and LTL formula φ there is k

s.t. $M \models \varphi$ iff $M \models_k \varphi$

Usage of Bounded Model Checking:

- ▶ Given desired property φ
- ▶ Check that $M \models_k \neg\varphi$.
- ▶ If yes: counterexample found.
- ▶ If no: increase k and repeat.

Propositional Encoding

Define propositional formula $\langle\langle M, \varphi \rangle\rangle^k$ in variables s_1, \dots, s_k ,
where each s_i is $s_{i,1}, \dots, s_{i,n}$.

Assignment to these variables $\hat{=}$ sequence of states in M .

$\langle\langle M, \varphi \rangle\rangle^k$ satisfiable iff $M \models_k \varphi$,

satisfying assignment $\hat{=}$ path π with $\pi \models_k \varphi$.

Propositional Encoding: Outer Structure

$\langle\langle M, \varphi \rangle\rangle^k$ is a conjunction $\langle\langle M \rangle\rangle^k \wedge \langle\langle \varphi \rangle\rangle^k$

$\langle\langle M \rangle\rangle^k$ enforces that s_1, \dots, s_k form a path π in M :

$$\langle\langle M \rangle\rangle^k := I(s_1) \wedge \bigwedge_{1 \leq i < k} T(s_i, s_{i+1})$$

$L_{k,\ell} := T(s_k, s_\ell)$ expresses: π is a (k, ℓ) -loop,

and $L_k := \bigvee_{\ell \leq k} L_{k,\ell}$: π is a k -loop.

$\langle\langle \varphi \rangle\rangle^k$ enforces that $\pi \models_k \varphi$:

$$\langle\langle \varphi \rangle\rangle^k := (\neg L_k \wedge \langle\langle \varphi \rangle\rangle_1^k) \vee \bigvee_{1 \leq \ell \leq k} (L_{k,\ell} \wedge \langle\langle \varphi \rangle\rangle_1^{k,\ell})$$

Propositional Encoding: Non-Loop Case

Formulas $\langle\langle \psi \rangle\rangle_i^k$ expressing $\pi \models_k^i \psi$
on non-loops are defined inductively:

$$\langle\langle p \rangle\rangle_i^k := p(s_i)$$

$$\langle\langle \neg p \rangle\rangle_i^k := \neg p(s_i)$$

$$\langle\langle X\psi \rangle\rangle_i^k := \begin{cases} \langle\langle \psi \rangle\rangle_{i+1}^k & \text{if } i < k \\ 0 & \text{otherwise.} \end{cases}$$

$$\langle\langle F\psi \rangle\rangle_i^k := \bigvee_{i \leq j \leq k} \langle\langle \psi \rangle\rangle_j^k$$

$$\langle\langle G\psi \rangle\rangle_i^k := 0$$

Propositional Encoding: Loop Case

Formulas $\llbracket \psi \rrbracket_i^{k,\ell}$ expressing $\pi^i \models_k \psi$ on a (k, ℓ) -loop are defined inductively:

$$\begin{aligned}\llbracket p \rrbracket_i^{k,\ell} &:= p(s_i) \\ \llbracket \neg p \rrbracket_i^{k,\ell} &:= \neg p(s_i) \\ \llbracket X\psi \rrbracket_i^{k,\ell} &:= \begin{cases} \llbracket \psi \rrbracket_{i+1}^{k,\ell} & \text{if } i < k \\ \llbracket \psi \rrbracket_\ell^{k,\ell} & \text{if } i = k \end{cases} \\ \llbracket F\psi \rrbracket_i^{k,\ell} &:= \bigvee_{\min(i,\ell) \leq j \leq k} \llbracket \psi \rrbracket_j^{k,\ell} \\ \llbracket G\psi \rrbracket_i^{k,\ell} &:= \bigwedge_{\min(i,\ell) \leq j \leq k} \llbracket \psi \rrbracket_j^{k,\ell}\end{aligned}$$

Optimization: getting rid of $\neg L_k$

Lemma

For all φ , and all $1 \leq i, \ell \leq k$,

$$\langle\langle \varphi \rangle\rangle_i^k \text{ implies } \langle\langle \varphi \rangle\rangle_i^{k,\ell}$$

Corollary

The formula $\langle\langle \varphi \rangle\rangle^k$ is equivalent to

$$\langle\langle \varphi \rangle\rangle_1^k \vee \bigvee_{1 \leq \ell \leq k} (L_{k,\ell} \wedge \langle\langle \varphi \rangle\rangle_1^{k,\ell})$$

Implicit Loop formulas

Improved translation:

- ▶ loop variables λ_i ; state that π is a (k, i) -loop.
- ▶ only one formula translation depending on loop variables.
- ▶ loop constraints to determine shape of the loop.

The translation is $\ll M, \varphi \gg^k := \ll M \gg^k \wedge \text{LOOP}_k \wedge \ll \varphi \gg_1^k$

The Loop constraints

LOOP_k is a conjunction $L_k \wedge A_k$

L_k determines the form of the loop:

$$L_k := \bigwedge_{i=1}^k (\lambda_i \rightarrow T(s_k, s_i))$$

A_k states that at most one λ_i is true, using new variables σ_i .

$$A_k := \bigwedge_{i=1}^k (\sigma_i \rightarrow \neg \lambda_i) \\ \wedge \neg \sigma_1 \wedge \bigwedge_{i=1}^{k-1} (\sigma_{i+1} \leftrightarrow \sigma_i \vee \lambda_i)$$

Encoding of the bounded semantics

$$\langle\langle X\psi \rangle\rangle_i^k := \begin{cases} \langle\langle \psi \rangle\rangle_{i+1}^k & \text{if } i < k \\ \bigvee_{j=1}^k (\lambda_j \wedge \langle\langle \psi \rangle\rangle_j^k) & \text{if } i = k \end{cases}$$

$$\langle\langle F\psi \rangle\rangle_i^k := \begin{cases} \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle F\psi \rangle\rangle_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\lambda_j \wedge \langle\langle F\psi \rangle\rangle_j^{k,2}) & \text{if } i = k + 1 \end{cases}$$

$$\langle\langle G\psi \rangle\rangle_i^k := \begin{cases} \langle\langle \psi \rangle\rangle_i^k \wedge \langle\langle G\psi \rangle\rangle_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\lambda_j \wedge \langle\langle G\psi \rangle\rangle_j^{k,2}) & \text{if } i = k + 1 \end{cases}$$

$$\langle\langle F\psi \rangle\rangle_i^{k,2} := \begin{cases} \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle F\psi \rangle\rangle_{i+1}^{k,2} & \text{if } i < k \\ \langle\langle \psi \rangle\rangle_k^k & \text{if } i = k \end{cases}$$

$$\langle\langle G\psi \rangle\rangle_i^{k,2} := \begin{cases} \langle\langle \psi \rangle\rangle_i^k \wedge \langle\langle G\psi \rangle\rangle_{i+1}^{k,2} & \text{if } i < k \\ \langle\langle \psi \rangle\rangle_k^k & \text{if } i = k \end{cases}$$

Linear CNF translation

Similar to Tseitin expansion, introduce variable for every $\langle\langle \psi \rangle\rangle_i^k$

Clauses of definition: equivalences expanded to CNF.

Example:

$$\langle\langle \mathbf{F}\psi \rangle\rangle_i^k \leftrightarrow \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_{i+1}^k$$

$$\rightsquigarrow \left(\langle\langle \mathbf{F}\psi \rangle\rangle_i^k \rightarrow \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_{i+1}^k \right) \\ \wedge \left(\langle\langle \psi \rangle\rangle_i^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_{i+1}^k \rightarrow \langle\langle \mathbf{F}\psi \rangle\rangle_i^k \right)$$

$$\rightsquigarrow \left(\neg \langle\langle \mathbf{F}\psi \rangle\rangle_i^k \vee \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_{i+1}^k \right) \\ \wedge \left(\neg \langle\langle \psi \rangle\rangle_i^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_i^k \right) \\ \wedge \left(\neg \langle\langle \mathbf{F}\psi \rangle\rangle_{i+1}^k \vee \langle\langle \mathbf{F}\psi \rangle\rangle_i^k \right)$$

Fairness and Liveness constraints

Fairness $\text{GF } \varphi$ and Liveness $\text{FG } \varphi$ constraints
can be encoded in a simpler way:

$$\begin{aligned} \llbracket \text{GF } \psi \rrbracket_i^k &:= \begin{cases} \llbracket \text{GF } \psi \rrbracket_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\lambda_j \wedge \llbracket \text{F}\psi \rrbracket_j^{k,2}) & \text{if } i = k + 1 \end{cases} \\ \llbracket \text{FG } \psi \rrbracket_i^k &:= \begin{cases} \llbracket \text{FG } \psi \rrbracket_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\lambda_j \wedge \llbracket \text{G}\psi \rrbracket_j^{k,2}) & \text{if } i = k + 1 \end{cases} \end{aligned}$$

Further simplification for Unary *LTL*

Simplified translation for the unary fragment with just F and G:

New variables Λ_i to state that s_i is on a loop.

$$\Lambda_1 \leftrightarrow \lambda_1 \wedge \bigwedge_{i=1}^{k-1} (\Lambda_{i+1} \leftrightarrow \Lambda_i \vee \lambda_{i+1})$$

Simpler translation:

$$\llbracket \mathbf{F}\psi \rrbracket_i^k := \begin{cases} \llbracket \psi \rrbracket_i^k \vee \llbracket \mathbf{F}\psi \rrbracket_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\Lambda_j \wedge \llbracket \psi \rrbracket_j^k) & \text{if } i = k + 1 \end{cases}$$

$$\llbracket \mathbf{G}\psi \rrbracket_i^k := \begin{cases} \llbracket \psi \rrbracket_i^k \wedge \llbracket \mathbf{G}\psi \rrbracket_{i+1}^k & \text{if } i \leq k \\ \Lambda_k \wedge \bigwedge_{j=1}^k (\Lambda_j \rightarrow \llbracket \psi \rrbracket_j^k) & \text{if } i = k + 1 \end{cases}$$

Simplified translation of fairness and liveness

Fairness and Liveness constraints in this simplified translation:

$$\begin{aligned} \ll \mathbf{GF} \psi \gg_i^k &:= \begin{cases} \ll \mathbf{GF} \psi \gg_{i+1}^k & \text{if } i \leq k \\ \bigvee_{j=1}^k (\mathcal{A}_j \wedge \ll \psi \gg_j^k) & \text{if } i = k + 1 \end{cases} \\ \ll \mathbf{FG} \psi \gg_i^k &:= \begin{cases} \ll \mathbf{FG} \psi \gg_{i+1}^k & \text{if } i \leq k \\ \mathcal{A}_k \wedge \bigwedge_{j=1}^k (\mathcal{A}_j \rightarrow \ll \psi \gg_j^k) & \text{if } i = k + 1 \end{cases} \end{aligned}$$